

**ABDULLAH GÜL UNIVERSITY
GRADUATE SCHOOL OF ENGINEERING & SCIENCE
ELECTRICAL AND COMPUTER ENGINEERING PROGRAM
COURSE DESCRIPTION AND SYLLABUS**

| Course Title | Code | Semester | T+L Hours | Credit | ECTS |
|----------------|---------|-------------|-----------|--------|------|
| LINEAR SYSTEMS | ECE-501 | FALL-SPRING | 3 + 0 | 3 | 10 |

Prerequisite Courses none

| | |
|--------------------------|---|
| Type | Elective |
| Language | English |
| Coordinator | Assoc. Prof. Dr. Günyaz Ablaý |
| Instructor | Assoc. Prof. Dr. Günyaz Ablaý |
| Adjunct | none |
| Aim | Learning, understanding and applying linear analysis and design tools that are needed in electrical engineering studies. |
| Learning Outcomes | <p>To give an opportunity to students for</p> <ul style="list-style-type: none"> • learning the fundamentals of linear systems • learning the stability theorems • learning linear control design with feedback • learning optimal design methods • learning discrete-time systems and related tools • learning software tools that can be used for analysis and design of nonlinear systems |
| Course Content | <ul style="list-style-type: none"> • Introduction to Linear Systems • State-space representation and analysis • Solution for state-space linear time-invariant (LTI) systems • Controllability and Observability • State Feedback Control • Optimal Control • Stability • Discrete-time systems • Design Considerations and Steady-state accuracy • MIMO systems • Passivity • Polynomial representations |

WEEKLY TOPICS AND PRELIMINARY STUDY

| Week | Topic | Preliminary Study |
|------|---|----------------------------|
| 1 | <p>Introduction and course overview</p> <ul style="list-style-type: none"> • System representation, Superposition principle • Analog vs. Digital signals and systems • Laplace solutions, Transfer functions, Block diagrams | The relevant lecture notes |
| 2 | <p>System representation and analysis</p> <ul style="list-style-type: none"> • State-space representations • Realizations • Linearization | The relevant lecture notes |
| 3 | <p>Solution for state-space linear time-invariant (LTI) systems</p> <ul style="list-style-type: none"> • Solution to homogeneous linear systems • State-transition matrix • Properties of the state transition matrix • Solution to nonhomogeneous linear systems | The relevant lecture notes |
| 4 | <p>Controllability and Observability</p> <ul style="list-style-type: none"> • Controllability and observability matrices • Canonical forms • Eigenvalues & Eigenvectors • Jordan Canonical form | The relevant lecture notes |
| 5 | <p>State Feedback Control</p> <ul style="list-style-type: none"> • Feedback control and estimations (observers) • Integral control • Observer-based control | The relevant lecture notes |
| 6 | <p>Optimal Control</p> <ul style="list-style-type: none"> • Performance index • Riccati solutions | The relevant lecture notes |

| | | |
|----|---|----------------------------|
| | <ul style="list-style-type: none"> • Kalman filter | |
| 7 | Stability <ul style="list-style-type: none"> • Definitions • Complex plane and Eigenvalues condition • Lyapunov Stability Theorem • Stability of nonlinear systems from local linearization | The relevant lecture notes |
| 8 | Midterm | |
| 9 | Discrete-time systems <ul style="list-style-type: none"> • Discrete equations • Stability • Discretization | The relevant lecture notes |
| 10 | Design Considerations and Steady-state accuracy <ul style="list-style-type: none"> • Performance requirements • Steady-state accuracy • Disturbance rejection | The relevant lecture notes |
| 11 | MIMO systems <ul style="list-style-type: none"> • Diagonal realizations • Controllability and observability • Controlling MIMO systems | The relevant lecture notes |
| 12 | Polynomial representations <ul style="list-style-type: none"> • Polynomial matrix • Smith and McMillian forms • Polynomial Control Design | The relevant lecture notes |
| 13 | Review Summary of the course, questions and answers | The relevant lecture notes |
| 14 | Final Exam | |

SOURCES

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|----------------------|---|
| Lecture Notes | Lecture notes and slides |
| | Course Textbook: J. Hespanha, <i>Linear Systems Theory</i> , Princeton University Press, 2009. |
| Other Sources | Additional Materials: |
| | 1. P. Antsaklis, A. Michel. <i>Linear Systems</i> . McGraw Hill, 1997. |

COURSE MATERIALS SHARING

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|------------------|---|
| Documents | Lecture notes, slides and papers |
| Homework | Students will be given one homework each week |
| Exams | 1 Midterm and 1 Final Exam |

EVALUATION SYSTEM

| SEMESTER STUDY | NUMBER | CONTRIBUTION |
|---------------------------------------|--------|--------------|
| Midterm | 1 | 20 |
| Homework | 14 | 25 |
| Quiz | 14 | 25 |
| SUB-TOTAL | | 70 |
| Contribution of Semester Study | | 70 |
| Contribution of Final Exam | 1 | 30 |
| TOTAL | | 100 |

Course Category

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|--------------------------|-----|
| Sciences and Mathematics | 30% |
| Engineering | 70% |
| Social Sciences | 0% |

RELATIONSHIPS BETWEEN LEARNING OUTCOMES AND PROGRAM QUALIFICATIONS

| | No Program Qualifications | Contribution Level | | | | |
|---|--|--------------------|---|---|---|----------|
| | | 1 | 2 | 3 | 4 | 5 |
| 1 | The skills of using mathematics, science and engineering information in advanced research, | | | | | X |

